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$\ddot{s} + s \dot{e} \dot{t} = s \ddot{e} \dot{t} + s^2 \rho e n$ (1.29) where ρ is the radius of curvature. Here $s \ddot{\cdot}$ is the tangential acceleration and s^2 / ρ is the centripetal acceleration. The angular velocity of the unit vector triad is directly proportional to \dot{s} . It is $\omega = \omega_t e_t + \omega_b e_b$ (1.30) where ω_t and ω_b are obtained from $\dot{e}_t = \omega_b e_n = s \dot{\cdot} \rho e n$ (1.31) $\dot{e}_b = -\omega_t e_n = s \dot{\cdot} d e_b / ds$ Note that $\omega_n = 0$ and also that $d e$

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Chronologically, "Classical Dynamics" was Donald Greenwood's second major publication on Analytical Dynamics, covering more advanced topics than the ones in "Principles of Dynamics," whose first edition preceded "Classical Dynamics" by some 12 years. "Classical Dynamics" is a somewhat more readable text, but just like its companion book, it fails to address issues like how one can use Lagrange's equations (or Hamilton's, for that matter) to correctly account for the effects of nonlinear ...

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